

THCS254 I2C/GPIO High Speed Bus Signal Transceiver

System Design Guidelines

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Example 1. I/O extension, Up/Down Stream synchronous mode

The primary chip performs parallel/serial conversion of input data using either the clock signal input to the REFIN pin or the built-in oscillator clock signal, whichever is selected, and outputs it from the TXP/N pin as a clock embedded serial signal. Secondary chip set to synchronous mode (SYNCEN pin = High) operate with clock signals regenerated from clock-embedded serial signals input to both the serial/parallel conversion circuit and the parallel/serial conversion circuit on the RXP/N pin. The Up/Down Stream will therefore have the same transmission bit rate.

Example 1 is an example of transmitting 10-bit GPIO data sampled asynchronously by the 20 MHz built-in oscillator clock on the Primary chip to the Secondary chip, and transmitting 10-bit GPIO data sampled asynchronously by the 20 MHz clock regenerated on the Secondary chip set to synchronous mode. This is an example of transmitting 10-bit GPIO data sampled asynchronously by a 20 MHz clock regenerated by the Secondary chip set to synchronous mode to the Primary chip.



When I2C is not used, all THCS254 settings are made at the setting terminals.

Power supply (*1)

The Primary chip (VDD1) and Secondary chip (VDD2) can be used with different supply voltages.

Data output control in start-up sequences

If I2C is not used, there are two options.

- Output enable control by OE pin (*2-1)



- Set to open drain output and pull-up with LVCMOS Receiver side I/O power supply (*2-2)

Disposal of unused terminals

Unused inputs should be fixed Low and outputs should be open.

Cable for connection between Primary chip and Secondary chip (*3)

Use twisted pair cables with a differential impedance of 100 Ω . Impedance error should be within ±10%, but this is not a limitation if the signal waveform observed near the RXP/RXN terminals meets the Eye opening described in the datasheet.

When unshielded twisted pair cables are bundled with other signal lines or power lines, data errors may occur due to crosstalk between the lines, resulting in malfunctions. Twisted pair cables must be shielded for each pair.



Example 2. I/O & I2C extension, Up/Down Stream asynchronous mode

The primary chip and secondary chip perform parallel/serial conversion with the REFIN pin input clock signal or the internal oscillator clock signal selected by each chip, and output from the TXP/N pin as clock embedded serial signals. Therefore, the bit rate of the Up/Down stream signal is based on the clock signal frequency selected for each chip.

Example 2 shows an example of transmitting I2C data in addition to GPIO data sampled at the falling edge of the clock signal input to each REFIN pin.

When using I2C, some settings (input/output direction, output buffer type, and digital filter settings) are set in registers.



■Power supply (*1)

The Primary chip (VDD1) and Secondary chip (VDD2) can be used with different supply voltages.

■ Data output control in start-up sequences (*2)

By fixing the OE pin to Low, all GPIO pins are disabled (Hi-Z) in the initial state immediately after power-on, avoiding unnecessary voltage application to the connected devices. From this state, set the input/output polarity and output buffer type of each GPIO pin using the GPIO_OEN and GPIO_OBUF registers, and then set the OVERRIDE_OE register to "1" to enable GPIO, overriding the register setting over the OE pin setting.

Step 1. All outputs disabled by OE pin = Low (Hi-Z)



Step 2. GPIO_OEN、 GPIO_OBUF, Set GPIO_I_FILTEN register as needed Step 3. OVERRIDE_OE register is set to "1"

■5V Tolerant I/O、Voltage Level Conversion (*3)

There are up to two 5V input and output pins each. In the above example, a signal output from a 5V-driven sensor is input to the 5V input terminal on the secondary chip side and output from the primary chip side at VDD1 voltage for 5V to VDD1 level conversion.

To use the 5V tolerant output pin as a 5V signal output, set the corresponding pin as an open drain and pull up to 5V externally.

■Disposal of unused terminals (*4)

Unused inputs should be fixed Low and outputs should be open.

Cable for connection between Primary chip and Secondary chip (*5)

Use twisted pair cables with a differential impedance of 100 Ω . Impedance error should be within ±10%, but this is not a limitation if the signal waveform observed near the RXP/RXN terminals meets the Eye opening described in the datasheet.

When unshielded twisted pair cables are bundled with other signal lines or power lines, data errors may occur due to crosstalk between the lines, resulting in malfunctions. Twisted pair cables must be shielded for each pair.



Example 3. I/O expansion with I2C

This mode uses I2C to control the state of each GPIO pin individually.



Power supply (*1)

The Primary chip (VDD1) and Secondary chip (VDD2) can be used with different supply voltages.

■ Data output control in start-up sequences (*2)

By fixing the OE pin to Low, all GPIO pins are disabled (Hi-Z) in the initial state immediately after power-on, avoiding unnecessary voltage application to the connected devices. From this state, set the input/output polarity and output buffer type of each GPIO pin using the GPIO_OEN and GPIO_OBUF registers, and then set the OVERRIDE_OE register to "1" to enable GPIO, overriding the register setting over the OE pin setting.

Step 1. All outputs disabled by OE pin = Low (Hi-Z)

Step 2. I2C_EXPAND register is set to "1"

- Step 3. GPIO_OEN、 GPIO_OBUF, Set GPIO_I_FILTEN register as needed
- Step 4. OVERRIDE_OE register is set to "1"

■5V Tolerant I/O、Voltage Level Conversion (*3)

There are up to two 5V input and output pins each. In the above example, a signal output from a 5V-driven sensor is input to the 5V input terminal on the secondary chip side and output from the primary chip side at



VDD1 voltage for 5V to VDD1 level conversion.

To use the 5V tolerant output pin as a 5V signal output, set the corresponding pin as an open drain and pull up to 5V externally.

■Disposal of unused terminals (*4)

Unused inputs should be fixed Low and outputs should be open.

Cable for connection between Primary chip and Secondary chip (*5)

Use twisted pair cables with a differential impedance of 100 Ω . Impedance error should be within ±10%, but this is not a limitation if the signal waveform observed near the RXP/RXN terminals meets the Eye opening described in the datasheet.

When unshielded twisted pair cables are bundled with other signal lines or power lines, data errors may occur due to crosstalk between the lines, resulting in malfunctions. Twisted pair cables must be shielded for each pair.



Design Guidelines for Power Supply

Insert filters (Ferrite Beads and Capacitors) in the Power Supply (**VDD** and **AVDD**). And insert Bypass Capacitor (0.1uF) in the Power Supply pins.

This device is equipped with a 1.2V built-in regulator. Insert Bypass Capacitors (CAPOUT: 10uF and CAPINA/CAPINP: 0.1uF) also for this regulator.

Bypass Capacitors should be attached just near the device. Insert the GND-Via to the Exposed-Pad to strengthen.







Design Guideline for High-Speed Signal

TXP/TXN and **RXP/RXN** are differential pairs of high-speed serial signals. Differential pairs should be closely spaced and coupled to eliminate common mode noise. Also, differential should be designed as 100Ω differential characteristic impedance (Zdiff).

The following is an example of microstrip line design. The high-speed signal lines trace in only single layer. The AC coupled capacitors should be attached just near the device.





Notices and Requests

1. The product specifications described in this material are subject to change without prior notice.

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